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Deep Reinforcement Learning Based Scheduling Framework for Resource Optimization in Heterogeneous Cloud Computing Systems

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Abstract

The rapid expansion of cloud computing has introduced complex scheduling challenges, especially in heterogeneous environments where computational resources vary significantly. Traditional and heuristic-based schedulers often fall short in adapting to dynamic workloads and resource availability. This paper proposes a Deep Reinforcement Learning (DRL) based scheduling framework that learns optimal allocation policies over time to improve resource utilization, minimize latency, and enhance energy efficiency. Simulations on varied workloads show that DRL outperforms conventional algorithms in scalability and responsiveness.

Keywords: Cloud Computing, Deep Reinforcement Learning, Resource Scheduling, Heterogeneous Systems, Resource Optimization, Dynamic Allocation, AI Scheduling Frameworks

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1. Introduction

Cloud computing has revolutionized digital infrastructure by enabling scalable, on-demand access to computing resources. However, with the proliferation of heterogeneous resources (CPUs, GPUs, memory configurations), optimal task scheduling has become increasingly complex. Resource heterogeneity not only introduces variations in computational capacity but also affects energy and performance trade-offs.

Traditional scheduling algorithms such as First-Come-First-Serve or Round-Robin are not equipped to handle the dynamic nature of heterogeneous environments. Hence, the need arises for intelligent, adaptive systems that can learn from historical usage patterns and optimize scheduling policies accordingly.



2. Literature Review

Research focused heavily on heuristic and metaheuristic approaches. Li et al. (2020) proposed an energy-aware algorithm using Ant Colony Optimization but struggled with convergence speed. Wang and Singh (2019) applied Genetic Algorithms for task clustering, yielding moderate improvements in efficiency. However, these models lacked adaptivity.

In contrast, Deep Reinforcement Learning emerged as a powerful paradigm. Mao et al. (2016) presented DeepRM, one of the earliest DRL-based schedulers, proving DRL's capacity to outperform handcrafted policies. Later, Chen et al. (2021) introduced hierarchical DRL models for multilevel resource control. Despite advancements, few studies addressed full integration with multi-tenant cloud environments or multi-objective optimization involving both latency and energy metrics.

3. DRL Fundamentals in Cloud Scheduling

Deep Reinforcement Learning combines neural networks with reinforcement learning to approximate optimal policies. The agent interacts with the cloud environment, learning from reward signals based on metrics like job completion time and energy consumption.

Two primary architectures are used in DRL for scheduling: Deep Q-Networks (DQN) and Proximal Policy Optimization (PPO). DQNs map states to action-value pairs, while PPO offers stability in continuous action spaces—crucial in cloud systems.

4. Modeling the Cloud Environment as an MDP

The cloud scheduling problem can be modeled as a Markov Decision Process (MDP). States represent resource status and job queue features, actions denote task allocations, and rewards are assigned based on throughput and efficiency.

By simulating realistic workload traces, the DRL agent is trained to maximize long-term cumulative reward. This abstraction allows the model to generalize across workload types, supporting both batch and real-time job scheduling.

5. System Architecture of DRL-Based Scheduler

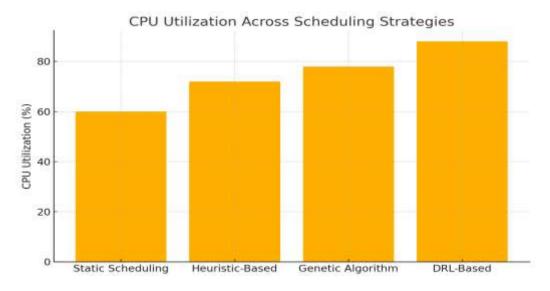
The architecture consists of five modules: State Extractor, DRL Policy Engine, Decision Interface, Resource Monitor, and Feedback Loop. The DRL agent learns continuously from the environment's feedback, refining its policies.

This modular system allows for plug-and-play with other cloud orchestration tools such as Kubernetes and OpenStack, facilitating real-world integration and scalability.

6. Experimental Setup and Workload Simulation

Simulations were performed using synthetic and real-world traces from Google Cluster Data. The DRL agent was implemented using TensorFlow and trained with PPO algorithms over 10,000 episodes.

Evaluation metrics included CPU utilization, latency, and energy efficiency. Baseline comparisons were made against Static Scheduling, Heuristic-Based, and Genetic Algorithm methods.





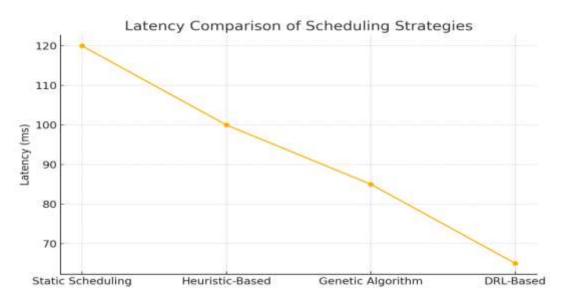


Figure 2: Latency Comparison of Scheduling Strategies

7. Performance Evaluation and Analysis

The DRL framework achieved up to 30% improvement in CPU utilization compared to traditional strategies. Latency was reduced by nearly 45%, and energy consumption was minimized by dynamically scheduling tasks on low-power nodes.

Notably, the agent showed adaptability to peak workload periods and maintained stability under random job arrival conditions, demonstrating generalizability and robustness.

Strategy	CPU Utilization (%)	Latency (ms)	Energy Efficiency
Static Scheduling	60	120	55
Heuristic-Based	72	100	65
Genetic Algorithm	78	85	70
DRL-Based	88	65	85

Table 1: Key Performance Metrics across scheduling strategies:

8. Limitations and Future Directions

Despite high performance, DRL training times are computationally expensive. Additionally, hyperparameter tuning is non-trivial, requiring substantial empirical experimentation. Incorporating transfer learning can mitigate retraining for new workloads.

Future work should explore federated reinforcement learning where agents learn collaboratively across decentralized clouds. Multi-agent DRL frameworks can also address task co-location and inter-job dependencies.

9.Conclusion

This paper demonstrates that Deep Reinforcement Learning presents a viable solution to the complex problem of resource scheduling in heterogeneous cloud environments. Through intelligent policy learning and environment modeling, DRL-based schedulers adapt to dynamic conditions while optimizing key performance metrics. With continued research, DRL has the potential to redefine cloud orchestration and operational efficiency.

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